



Measuring transducers MI4x0 series
Programmable transducers for RTD sensors
MI450

- Measuring of resistance of RTD sensors (Pt100, Pt1000, Ni100, Cu10, ...)
- Accuracy class up to: 0.5
- Programmable input and output
- Serial communication RS232 or RS485, MODBUS protocol
- Universal AC/DC or AC Auxiliary power supply

PROPERTIES

- Measuring of resistance of RTD sensors (Pt100, Pt1000, Ni100, Cu10*, ...)
- Accuracy class: 0.5 (Cu10 - Accuracy class: 1*)
- Programmable input and output
- Serial communication RS232 or RS485, MODBUS protocol
- Universal AC/DC or AC Auxiliary power supply
- (very high speed data rate: up to 115,200 bit/s, MODBUS protocol)
- Low power consumption
- Housing for DIN rail mounting
- Correspond to EN 60770-1: 1999

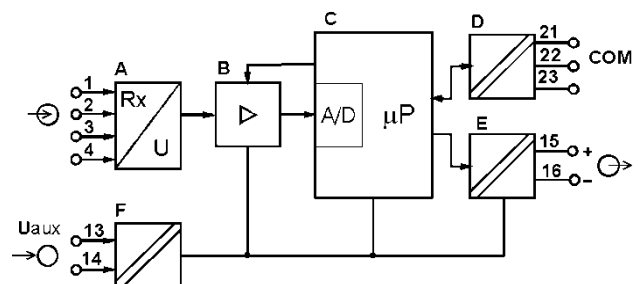
*See chapter Technical data - Accuracy.

APPLICATION

Measuring transducer MI450 is designed for use in industrial process for conversion of nonlinear resistance sensors (RTD – sensors) in to appropriate DC current or DC voltage signal. The analogue output signal is proportional to the measured value and it is appropriate for regulation of analogue and digital devices with reasonable dependence on environmental conditions, where they are planned to be used.

LAYOUT AND MODE OF OPERATION

Resistance on the input terminals can be measured with three methods, two, three or four wire connection. In all cases U-I method is used for measuring. Enforced current causes a voltage drop (A - Picture 2) on measured RTD sensor which is supplied to the programmable amplifier B. After A/D conversion the signal is computed in microprocessor C. The measured value determined by the microprocessor is assigned to the programmable analogue output E. Communication D enables programming of the measuring transducer and monitoring of the measuring resistance on the input terminal. Communication, analogue output and auxiliary power supply are electrically insulated from other system by means of separation transformer.



Picture 1: Block diagram

PROGRAMMING

Input and output values are programmed¹⁾ with MiQen setting software via RS232 or RS485 communication. Before setting the transducer, output value must be selected by the jumpers on the output module²⁾. It is possible to choose between three ranges 0...±10 V, 0...±5 mA and 0...±20 mA. Within this three ranges it is possible to set any linear or bent (with maximum 5 break points) output characteristic.

¹⁾ – Programming is not possible in versions without communication

²⁾ – Qualified person only

VERSIONS

The following transducer versions are available as programmable via communication or to be specified at the placing order:

Input	Type of RTD	Measuring voltage	Output	Supply	Communication	Bent characteristic of analogue output
-200° to 850°C for Pt..., -60° to 250°C for Ni..., 20Ω to 10kΩ for polinom ³⁾ , -50° to 250°C for Cu...	Pt100 Pt1000 Ni100 Cu10*	< 2.2 V	1 mA 5mA 10 mA 20 mA 4...20 mA 1 V 10 V other on request	Universal or AC: 57 V 100 V 230 V 400 V 500 V	RS232 or RS485	Programmable via communication or to be specified at the placing order

Table 1: Versions of MI450

³⁾ – With program package MiQen it is possible to set 6th grade polynomial function

*Cu10: Accuracy class 1; see chapter Technical data.

Transducers are mounted on standard rail 35 x 15 mm (according to DIN EN 50022)

TECHNICAL DATA

GENERAL:

- Measured quantity: temperature from RTD sensor
- Measured principle: microprocessor sampling

INPUT:

- Measuring method: two wire connection
three wire connection
four wire connection
- Input range with programmable ratings:
RTD sensors limit values: Measuring voltage: $< 2.2 \text{ V}$
 20Ω to $10 \text{ k}\Omega$
- Minimum temperature range⁴⁾: 100° K
- Minimum differential resistance⁵⁾: 40Ω ($100\Omega \rightarrow 140\Omega$)
- Lead resistance: $< 10 \Omega$ per lead
- Consumption: $< 0.5 \text{ VA}$

⁴⁾ – Cu10: 80° K

⁵⁾ – Cu10: 3Ω ($10\Omega \rightarrow 13\Omega$)

ANALOGUE OUTPUT:

Programmable DC current output:

- Output I_{OutN} (output range end value):
- Output range values⁶⁾: $0 \dots \pm 1 \text{ mA}$ to $0 \dots \pm 5 \text{ mA}$ or,
 $0 \dots \pm 5 \text{ mA}$ to $0 \dots \pm 20 \text{ mA}$
- Burden voltage: 15 V
- External resistance: $R_{B\text{max.}} [\text{k}\Omega] = \frac{15 \text{ V}}{I_{\text{OutN}} [\text{mA}]}$

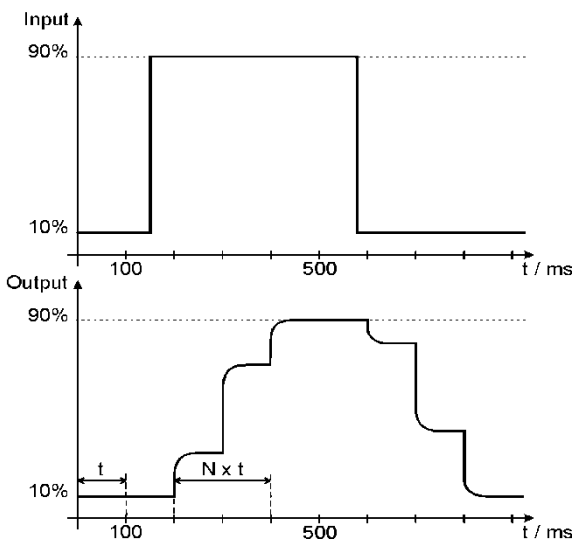
⁶⁾ – Depends of set jumpers on output module

Programmable DC voltage output:

- Output U_{OutN} (output range end value):
- Output range values $0 \dots \pm 1 \text{ V}$ to $0 \dots \pm 10 \text{ V}$
- Burden current: 20 mA
- External resistance: $R_{B\text{min.}} [\text{k}\Omega] = \frac{U_{\text{OutN}} [\text{V}]}{20 \text{ mA}}$

General:

- Response time: programmable from 0.5 s to 60 s
- Residual ripple: $< 1 \%$ p.p.
- Maximum output value: limited at 125%



Picture 2: Output transfer characteristic

N – Number of sliding windows

t – Sampling time

The output may be either short or open-circuited and it is electrically insulated from all other circuits (floating).

All the output range end values can be reduced subsequently using the programming software, but a supplementary error results.

ACCURACY:

- Reference value: Input range end value
 - Accuracy class:
 - Analogue output^{7),8)}: Temperature 0.5 c
 - Communication⁸⁾: Temperature 0.5
- ⁷⁾ – To calculate intrinsic error, see chapter intrinsic-error (for analogue outputs) on this page.
⁸⁾ – Cu10: Accuracy class 1, due to low resistance range ($10\Omega \rightarrow 13\Omega$).

Reference conditions:

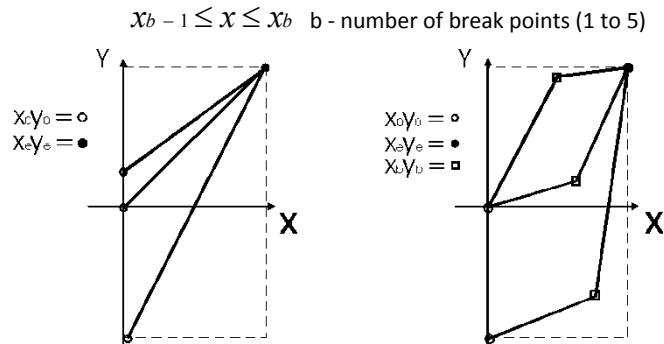
- Ambient temperature: $15 \dots 30^\circ \text{ C}$
- Input: $0 \dots 100 \%$ R_N

Intrinsic-error (for analogue outputs):

For intrinsic-error for analogue outputs with bent or linear-zoom characteristic multiply accuracy class with correction factor (c).
Correction factor c (the highest value applies):
Linear characteristic

$$c = \frac{1 - \frac{y_0}{y_e}}{1 - \frac{x_0}{x_e}} \text{ or } c = 1$$

Bent characteristic



-- Limit of the output range

Picture 3: Examples of settings with linear and bent characteristic

POWER SUPPLY:

Auxiliary AC/DC voltage (universal):

- Rated voltage (U_r): $24 \dots 300 \text{ V DC}$
 $40 \dots 276 \text{ V AC}$
- Frequency range: $40 \dots 70 \text{ Hz}$
- Power consumption: $< 3 \text{ VA}$

Auxiliary AC voltage:

Rated voltage (U_r)	Rated operating range
57.74 V	80...120 % U_r
100 V	
230 V	
400 V ⁹⁾	
500 V ⁹⁾	

⁹⁾ – to 300 V installation category III, from 300 to 500 V installation category II – see chapter Regulations.

Table 3: Rated AC voltage for Auxiliary power supply

- Frequency range: $45 \dots 65 \text{ Hz}$
- Power consumption: $< 3 \text{ VA}$

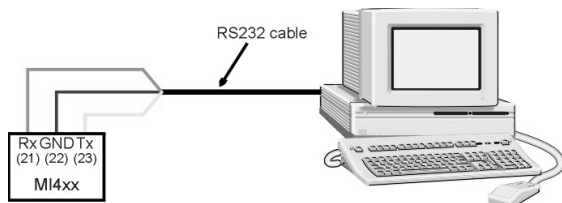
COMMUNICATION (OPTIONAL):

RS232

- Connection type: Point to point
- Signal levels: RS232
- Maximum cable length: 15 m
- Connector: Screw terminals
- Isolation: 3.7 kV rms for 1 minute between all terminals and all other circuits, except between communication terminals and output terminals, 2 kV rms for 1 minute
- Transmission mode: Asynchronous
- Message format: MODBUS RTU
- Data rate (very high speed): 1.200 to 115.200 bits/s
- RS232 connections

MI450	9 pin D connector (PC)	25 pin D connector (PC)
Rx (21)	Tx (3)	Tx (2)
⏏ (22)	GND (5)	GND (7)
Tx (23)	Rx (2)	Rx (3)

Table 4: RS232 connections



Picture 4: Connection of MI450 on PC via RS232 communication

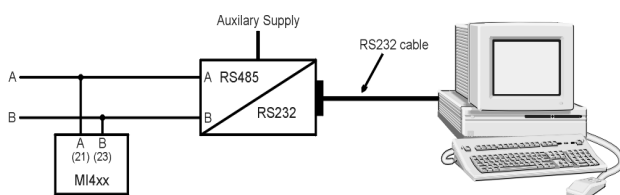
RS485

- Connection type: Multi-drop (32 connections per link)
- Signal levels: RS485
- Cable type: Screened twisted pair
- Maximum cable length: 1000 m
- Connector: Screw terminals
- Isolation: 3.7 kV rms for 1 minute between all terminals and all other circuits, except between communication terminals and output terminals, 2 kV rms for 1 minute
- Transmission mode: Asynchronous
- Message format: MODBUS RTU
- Data rate (very high speed): 1,200 to 115,200 bits/s
- RS485 connections

MI450	RS485
A (21)	DATA +
C (22)	NC ¹⁰⁾
B (23)	DATA -

Table 5: RS485 connections

¹⁰⁾ – NC – do not connect



Picture 5: Connection of MI450 on RS485 communication line

HOUSING:

- Material of housing: PC/ABS
unflammable, according to **UL 94 V-0**
- Mounting: For rail mounting, 35 x 15 mm
according to **DIN EN 50022: 1978**
- Enclosure protection: IP 50
(IP 20 for connection terminals)
according to **EN 60529: 1989**
- Weight: Approx. 300 g

CONNECTION TERMINALS:

- Permissible cross section of the connection leads:
≤ 4.0 mm² single wire
2 x 2.5 mm² fine wire

REGULATIONS:

- Protection: Protection class II
300 V rms, installation category III
500 V rms, installation category II
Pollution degree 2
- Test voltage: 3.7 kV rms
according to **EN 61010-1: 1990**

ENVIRONMENTAL CONDITIONS:

- Climatic rating: Climate class 2 acc. to
EN 60688: 1992
- Operating temperature: -10 to +55 °C
- Storage temperature: -40 to +70 °C
- Annual mean relative humidity: ≤ 75% r.h.

EU DIRECTIVES CORRESPONDING FOR CE MARKING

Low voltage directive **73/23/EEC**:

EN 61010-1: 1993 and **EN 61010-A3: 1995**

Safety requirements for electrical equipment for measurement, control, and laboratory use, Part 1: General requirements

EMC directive **89/336/EEC**:

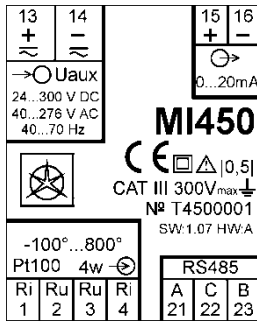
EN 61326-1: 1997

Electrical equipment for measurement, control, and laboratory use EMC requirements, Part 1: General requirements.

Commentary: If strong HF electromagnetic fields are expected in the place where transducer will be used, usage of 5mA analogue output is recommended, because in that case field influence on the transducer is the lowest.

Marking

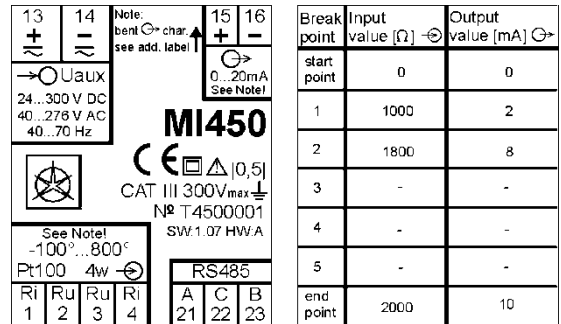
Measuring transducers with linear characteristic:
One label at the front of housing (Picture 7a):



Picture 6a: Example of label for transducer with linear characteristic

Measuring transducers with bent characteristic:

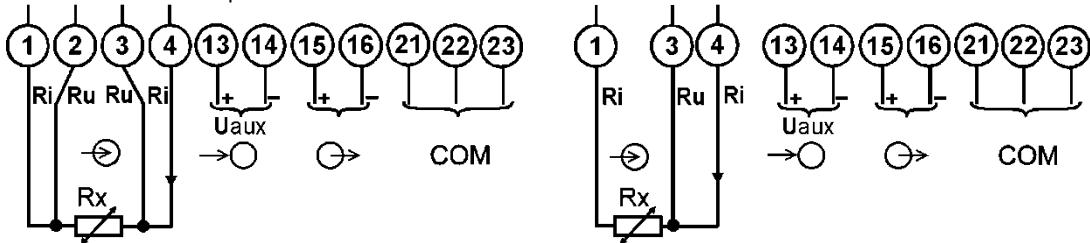
One label at the front of the housing and additional label at the top of the housing (Picture 7b):



Picture 6b: Example of label for transducer with bent characteristic

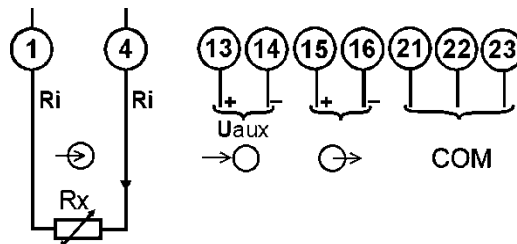
CONNECTION

Type of connection can be specified with the order or changed via communication with MiQen software. The connection terminals marking can be found on the front plate.



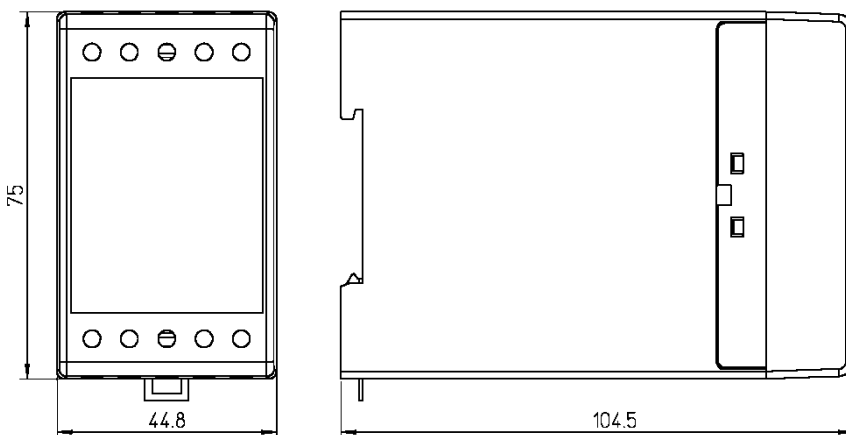
Picture 7a: Connection diagram 4-wire

Picture 7b: Connection diagram 3-wire



Picture 7c: Connection diagram 2-wire

DIMENSIONAL DRAWING



Picture 8: Dimensional drawing (all dimensions are in mm)

SPECIFICATION AND ORDERING INFORMATION

For ordering it is necessary to declare type of the transducer (MI450), type of RTD sensor or polynomial function, measuring range, output quantity and range, type of power supply, type of communication and shape of output characteristic.

ORDERING CODE:

MI450 b; c; d...e F; G; H(i V); J; K

MI450	Value	Code
b	Type of sensor or input polynomial function of X^6 order Pt100; Pt1000; Ni100; Cu10* ...	b
c	Measuring range: -200° to 850° C (depends of sensor type) 20 Ω to 10 kΩ (for polynomial function)	-200° ≤ c ≤ 850° 20 Ω ≤ c ≤ 10 kΩ
d	Start value of output signal -20...20 - current output -10...10 - voltage output	-20 ≤ d ≤ 20
e	End value of output signal 0...20 - current output 0...10 - voltage output	1 ≤ e ≤ 20
F	Type of output signal current - mA voltage - V	mA V
G	Type of connection 2 - wire 3 - wire 4 - wire	2 3 4
H	Type of power supply universal power supply AC power supply	U A
i	Value of power supply voltage (only for AC power supply) 57 V 100 V 110 V 230 V 300 V	57 100 110 230 300
J	Type of communication RS 232 RS 485 no communication	2 4 0
K	Type of output characteristic linear ¹¹⁾ bent 1...5 (number of break points) Voltage - V	L 1 ≤ l ≤ 5 V

Table 6: Ordering information

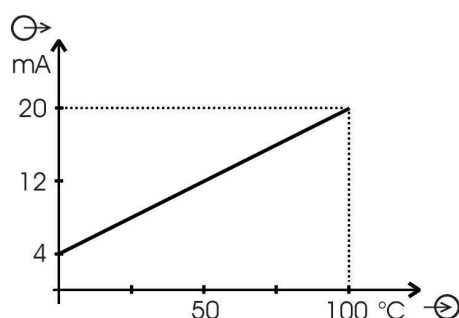
*Cu10: Accuracy class 1; see chapter Technical data - Accuracy.

¹¹⁾ - For ordering code for bent characteristic see additional ordering information Table 7.

ORDERING EXAMPLE FOR TRANSDUCER WITH LINEAR OUTPUT CHARACTERISTIC

Measuring transducer MI450, for Pt100 RTD sensor with temperature range 0...100 C, output range 4...20 mA, 4-wire connection, 110 V AC power supply, communication RS232 and linear output characteristic (Graph 1).

MI450 Pt100; 0...100°; 4...20 mA; 4; A 110 V; 2; L.



Graph 1: Example of linear output characteristic

Additional ordering information

For ordering transducer with bent characteristic it is necessary to declare breaking points in output characteristic (maximum 5 breaking points).

Ordering code for transducers with bent output characteristic:

MI450 b; c; d...e F; G; H(i V); J; K($l_1/m_1; l_2/m_2; \dots$)

MI450	Value	Code
l	value of input quantity	-200° ≤ l ≤ 850° or 20 Ω ≤ l ≤ 10 kΩ (depends of measuring range and type of RTD sensor)
m	value of output quantity when input value is k	-20...20 (depends of output range) -20 ≤ m ≤ 20

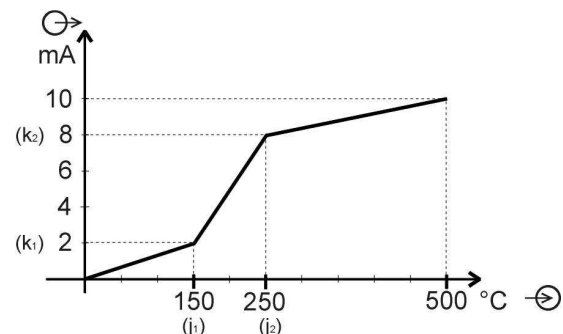
Table 7: Ordering information for bent characteristic

The sequence of breaking points must rise with measured quantity.

ORDERING EXAMPLE FOR TRANSDUCERS WITH BENT OUTPUT CHARACTERISTIC

Measuring transducer MI450 for Pt100 RTD sensor with temperature range 0...500°C, output range 0...10 mA, 4-wire connection, universal power supply, communication RS485 and bent output characteristic. The transducer is zooming the range from 150°C to 250°C (Graph 2)

MI450 Pt100; 0...500°; 0...10 mA; 4; U; 4; 2(150/2; 250/8)



Graph 2: Example of bent output characteristic with two breaking points

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